

Controls

Control A:	Yaw	Expo	0%	Dualrate	+60%	[Off]
		Travel	+100%	Travel	+100%	
		Centre	+28%			
Control B:	Nose U/D	Expo	0%	Dualrate	+60%	[Off]
		Travel	+100%	Travel	+100%	
		Centre	+8%			
		Transit	- 0.0s	Transit	+ 0.0s	
Control C:	Roll	Expo	0%	Dualrate	+60%	[Off]
		Travel	+100%	Travel	+100%	
		Centre	+7%			
Control D:	Pitch	Expo	0%	Dir Thr	[Off]	
		Travel	+75%	Travel	- +100%	
		Centre	0%	Thr Curv	5 Pt	
		P+	+75%	H+	+70%	
		HP	+45%	H-	+25%	
		IU	+20%			
		Transit	- 0.0s	Transit	+ 0.0s	
Control E:	Unused					
Control F:	Throttle	Idle Trm	-30%	Fix Val	0%	[LS Dn]
		Transit	- 0.0s	Transit	+ 0.0s	
Control G:	Unused					
Control H:	Unused					
Control I:	Unused					

Servos

Servo 1:	Roll	Centre		+10,%		
		Roll	(+Tr)	+85%	+75%	[On]
		Limit		100%	100%	
Servo 2:	Nose U/D	Centre		+5,%		
		Nose U/D	(+Tr)	-75%	-75%	[On]
		Limit		100%	100%	
Servo 3:	Tailrot	Centre		0,0%		
		Pitch	(+Tr)	-40%	-25%	[On]
		Yaw	(+Tr)	-90%	-90%	[On]
		Fix.Val	(+Tr)	0%	0%	[Off]
		Limit		100%	100%	
Servo 4:	Pitch	Centre		+10,%		
		Pitch	(+Tr)	+85%	+110%	[On]
		Limit		110%	100%	
Servo 5:	Throttle	Centre		0,0%		
		Throttle	(+Tr)	+60%	+75%	[On]
		Limit		100%	100%	
Servo 6:	Unused					
Servo 7:	Unused					
Servo 8:	Unused					
Servo 9:	Unused					

Combi Switch

Aileron follows Rudder	0%	[Off]
------------------------	----	-------

---

**Gx Switch**

Control H: 0%

---

**Teacher/Pupil**

Control A - Yaw - Controls Pupil Servo - Unused  
Control B - Nose U/D - Controls Pupil Servo - Unused  
Control C - Roll - Controls Pupil Servo - Unused  
Control D - Pitch - Controls Pupil Servo - Unused

---

**Timer**

Timer Switch is [Off]  
Timer Start is set to 00:00  
Timer Alarm is set to 00:00

---

**Tachometer**

0 Blade

---

**Servo Test**

Servo 0: Unused

---

**Modulation**

PPM9

---